



WARRANTY IS LIMITED TO THE BEST OF OUR KNOWLEDGE AND BELIEFS.



Acknowledgements

I

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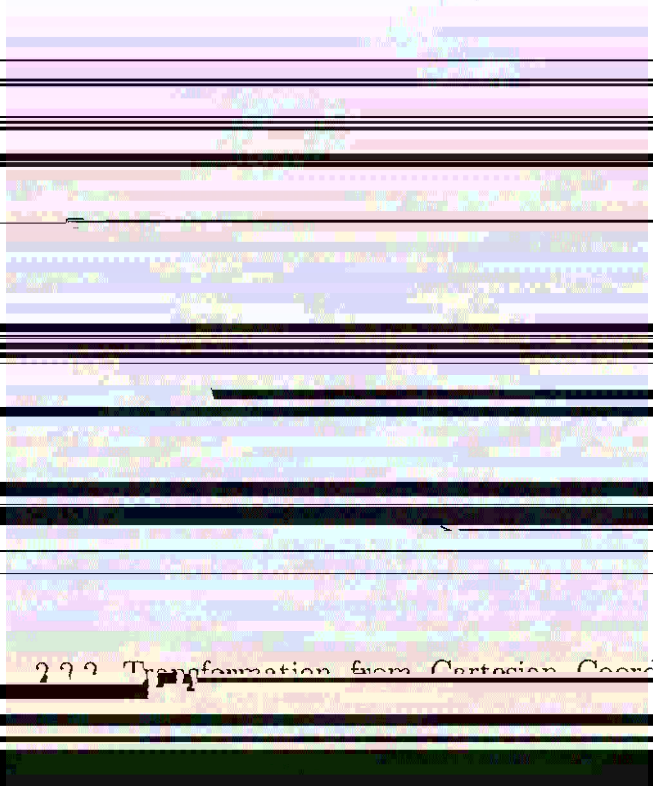
Acknowledgements

III

List of Figures

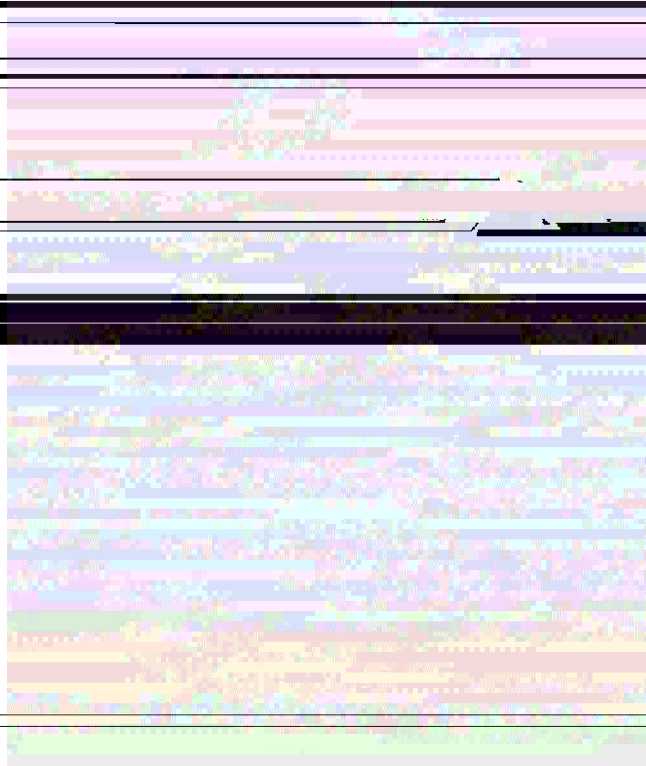
VII

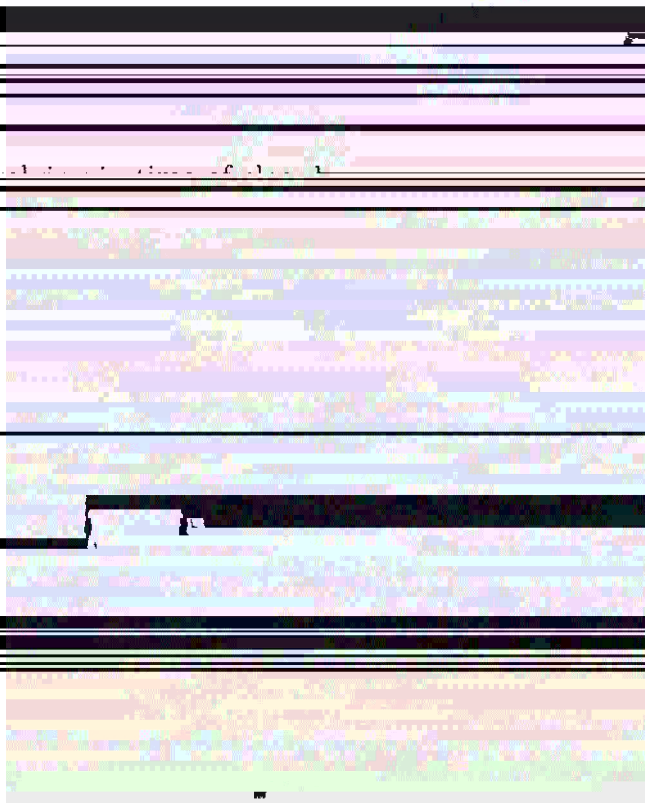
Contents (Continued)



2.2.2 Transformation from Cartesian Coordinates (x, y) to

Generalized Curvilinear Coordinates (φ, ψ)	21
2.2.3 The Equations in New Generalized Curvilinear Coordi	





List of Figures (Continued)

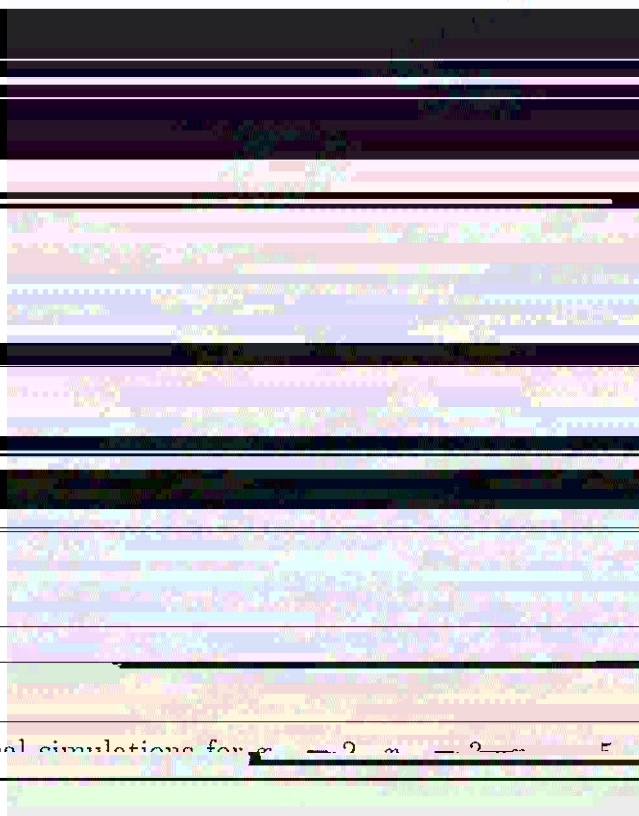
Figure	Page
2.22 Physical domain.	58
2.23 Pressure contours for $T = W = D = 1$ and $\Delta P = 0.01$.	62
2.24 Pressure contours for channel with $\epsilon = 1$, $W = D = 1$ and $\Delta P = 0.01$.	62

List of Figures (Continued)

Figure

Page

2.26. Pressure contours for channel flow. $U_0 = 1$, $H = 1$, $D = 1$, $\nu = 0.01$



ical simulations for $\nu = 0.01$, $\nu = 0.001$, $\nu = 0.0001$, $\nu = 0.00001$





Figure

Page

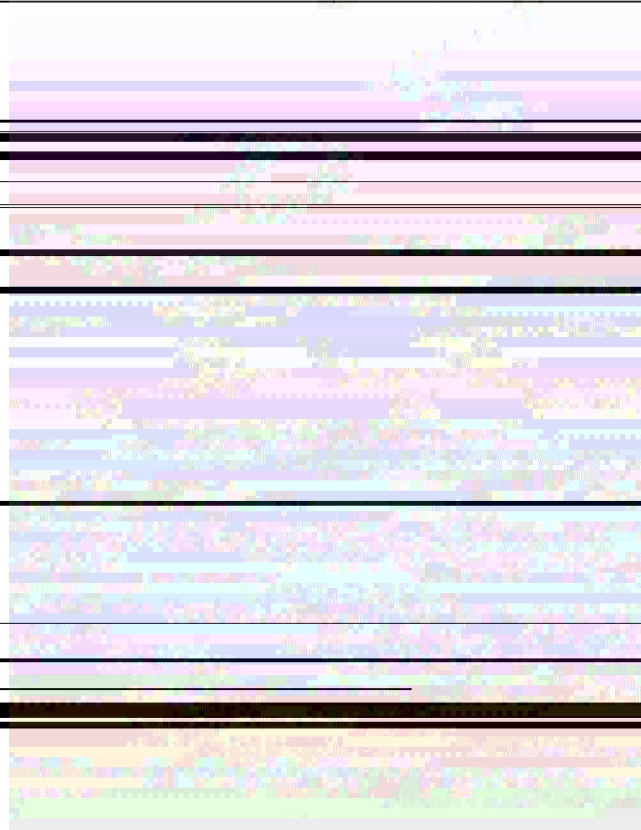
291 The pressure along lower boundary of channel with $\alpha = 2.0$, $\nu = 1$

Types of Sentences



incompressible fluid flow through a bounded domain with the inflow and outflow parts of boundaries have not yet been considered in detail. The goal of this thesis is to study the numerical methods for approximating solutions of such

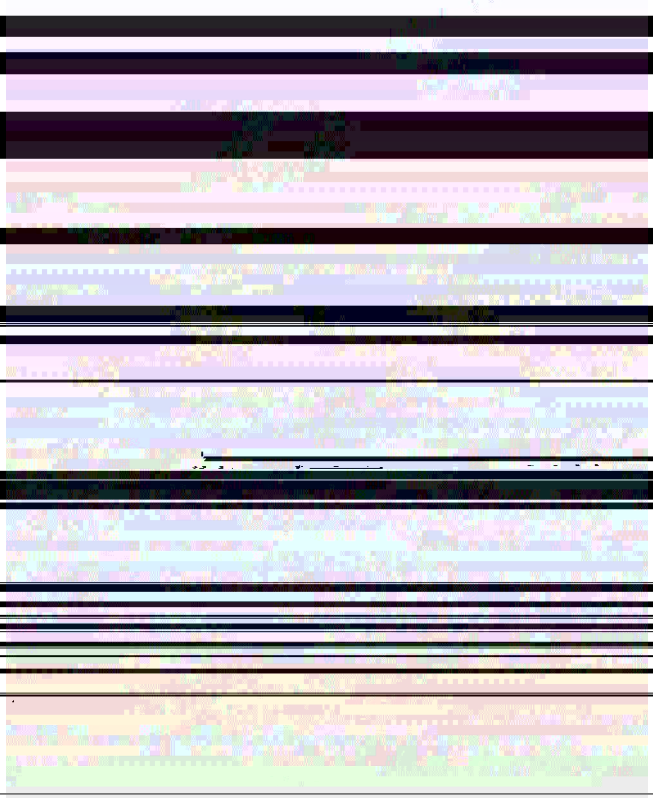
flowing-through problems.



tions

This section has an introductory nature, wherein we discuss the funda-

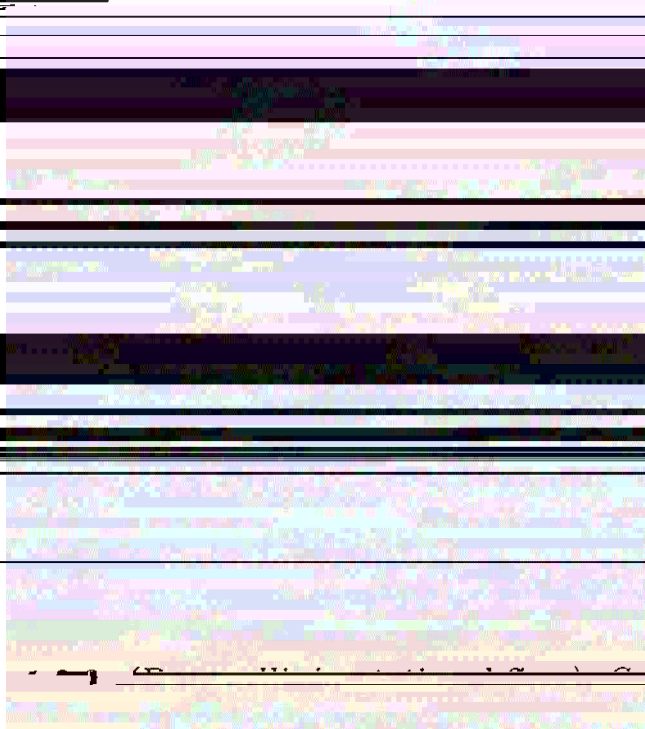






$$\mathbf{u} = (u_1, u_2, 0), \quad u_i = u_i(x_1, x_2)$$

only the third component of the vorticity $\omega_3 = \omega$ is present and the right-hand

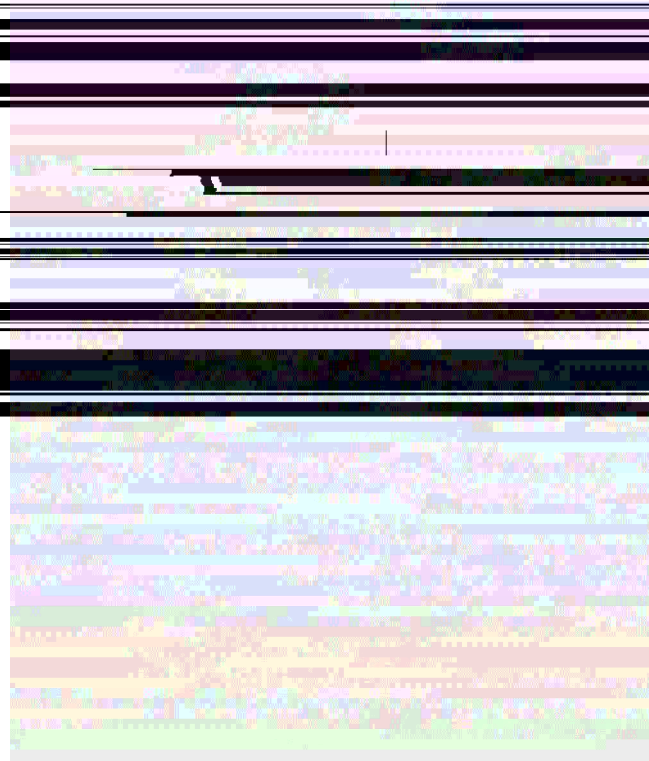


17

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Figure 1.9: Normal vector on surface





Books in fluid mechanics such as C.K. Batchelor (1970) J. Serrin (1950)

Through Problems

Will you be able to solve these problems? 11 1 11

Γ_2^0 Γ^2

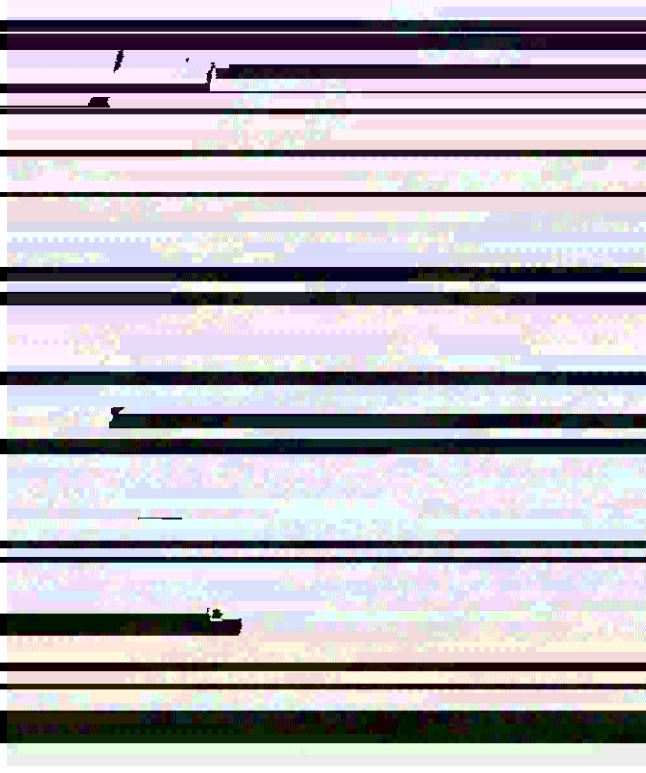
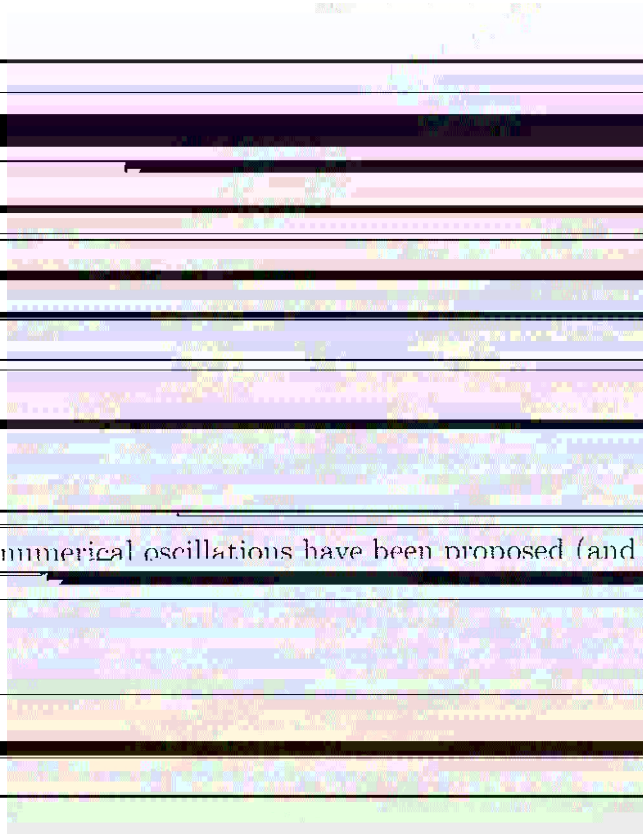


Figure 1.4: Sketch of a domain.



situation is not only very mathematically interesting but also corresponding to





eration of numerical oscillations have been proposed (and successfully employed)

following the Flux-Corrected Transport (FCT) concept developed by Boris and



component of the velocity vector and the tangent components of the vorticity
are given on the inflow part of the domain boundary. We utilize the non



where $u(x, y)$ and $v(x, y)$ are components of the velocity vector in the x and y di-



we set the density equal to one ($\rho = 1$).

$x \uparrow$

$y \uparrow$ $\mathbf{u} = (u \ v)$

$$\begin{aligned} q &= q_1(x, y), \\ w &= w_1(x, y). \end{aligned} \quad (2.2.5)$$

Outflow part CD: $(x, y) \in \Gamma^2$

Find the solution of equations (2.2.1)–(2.2.2) with the following boundary conditions:

Irreversible boundaries AD and BC: $(\varphi) \in C^1 \cap C^2$

tions:

Irreversible boundaries AD and BC: $(\varphi) \in C^1 \cap C^2$

$$\left(\frac{\partial u}{\partial x}\right)\left(\frac{\partial v}{\partial x}\right) + u\frac{\partial^2 v}{\partial x^2} + \left(\frac{\partial v}{\partial x}\right)\left(\frac{\partial v}{\partial y}\right) + v\frac{\partial^2 v}{\partial x\partial y} = -\frac{\partial^2 P}{\partial y\partial x}.$$



$$\frac{\partial^2 P}{\partial x^2} = \frac{\partial^2 P}{\partial x^2}$$

We have

$$\left(\frac{\partial w}{\partial q} \right)$$

after simplification, we obtain

$$P_{11} - P_{12} - P_{21} + P_{22} > 0$$

(1.1.1)

(1.1.1)



$$x = x(\varphi, \psi), \quad y = y(\varphi, \psi).$$

The diagram shows a coordinate system with a curve and a point. The curve is defined by the parametric equations $x = x(\varphi, \psi)$ and $y = y(\varphi, \psi)$.

$$dx = \frac{\partial x}{\partial \varphi} d\varphi + \frac{\partial x}{\partial \psi} d\psi.$$

$$dy = \frac{\partial y}{\partial \varphi} d\varphi + \frac{\partial y}{\partial \psi} d\psi.$$

or in a matrix form

$$\begin{bmatrix} dx \\ dy \end{bmatrix} = \begin{bmatrix} \frac{\partial x}{\partial \varphi} & \frac{\partial x}{\partial \psi} \\ \frac{\partial y}{\partial \varphi} & \frac{\partial y}{\partial \psi} \end{bmatrix} \begin{bmatrix} d\varphi \\ d\psi \end{bmatrix}.$$

Solving this matrix equation, for the right-hand column matrix, we have

$\partial\varphi \quad \partial\varphi$



On 11/11/11, I / A. Khan, and in my not equal to you. Finally, we now

$$\frac{1}{\phi} \frac{\partial w}{\partial \varphi} + cw^2 \frac{\partial q}{\partial w} = 0.$$



The second step: We have to use the condition

$$\frac{\partial^2 \varphi}{\partial w^2} = \frac{\partial^2 \varphi}{\partial \varphi^2} \quad (2.2.26)$$

and $\psi|_D$ and $\psi|_{\partial D}$ are constants. The function $\psi(r, \theta)$ is determined up to an

arbitrary constant, and without loss of generality, we can choose

$$\psi|_{AD} = \psi(A) = \text{const.}$$

into equation (2.2.31) yields

$$(y_{\zeta} - y'_{AB}(x)x_{\varphi}) d\varphi + (y_{\psi} - y'_{AB}(x)x_{\psi}) d\psi = 0. \quad (2.2.32)$$

In (φ, ψ) -plane, equation (2.2.32) is ODE for unknown function $\varphi_{A'B'}(\psi)$



$P_2(x, u)$, $(x, u) \in \Gamma_2$. Here, the situation is slightly more complicated. Let us

assume that equation of boundary $C'D'$ is given by the formula

and the equation of boundary CD is given by the formula

In order to summarize, we write the formulation of problem 3' and problem 2'

in a compact form in terms of new unknown functions and new independent variables (φ, ϵ) .

Problem 3':

$$\varphi_{A'B'}(0) = 0, \quad (2.2.45)$$

$$w = w(\varphi, \psi), \quad \varphi = \varphi_{A'B'}(w)$$

$\psi_{A'B'} = \psi_{A'B'}(w)$

$$\frac{dq}{dw}$$

$$\begin{aligned}
 \varphi_{A'B'}(0) &= 0 & (2.2.49) \\
 q &= q_1(\varphi, \psi), & \varphi = \varphi_{A'B'}(\psi) \\
 w &= w_1(\varphi, \psi), & \varphi = \varphi_{A'B'}(\psi)
 \end{aligned}$$

$$B'C' : \rho(l, 0) = \rho_0, \quad \rho_0 \neq 0$$

$$\frac{dq}{dl} = k_{BC}(l), \quad (2.2.50)$$

↓ $\rho(l, 0) = \rho_0, \quad \rho_0 \neq 0$



The following information is classified (S) (0.0.40) (0.0.44) and is to be controlled as follows:



$$\Psi \uparrow$$

$B' \xrightarrow{h\varphi} 1 C' \cdot \varphi$

$N.L.$



approximate the integral $\int_{x_i}^{x_{i+2}} (q_G) dx$



$$i = N_1 - 2, \dots, 1.$$

$$\left(\frac{1}{N} \sum_{j=1}^N q_{i_0, j+1} - q_{i_0, j-1} \right)$$



When the values $u(n)$ and $d(n)$ are found for all grid points, we can solve

of $\tilde{z}^{(n)}$ after iteration

$$\tilde{z}^{(n)} = \tilde{z}^{(n-1)} + \int_{t_{j-1}}^{t_j} f(t, \tilde{z}^{(n-1)}) dt$$

where $\tilde{z}^{(n)}$ denotes the value of \tilde{z} at t_j after n iterations.

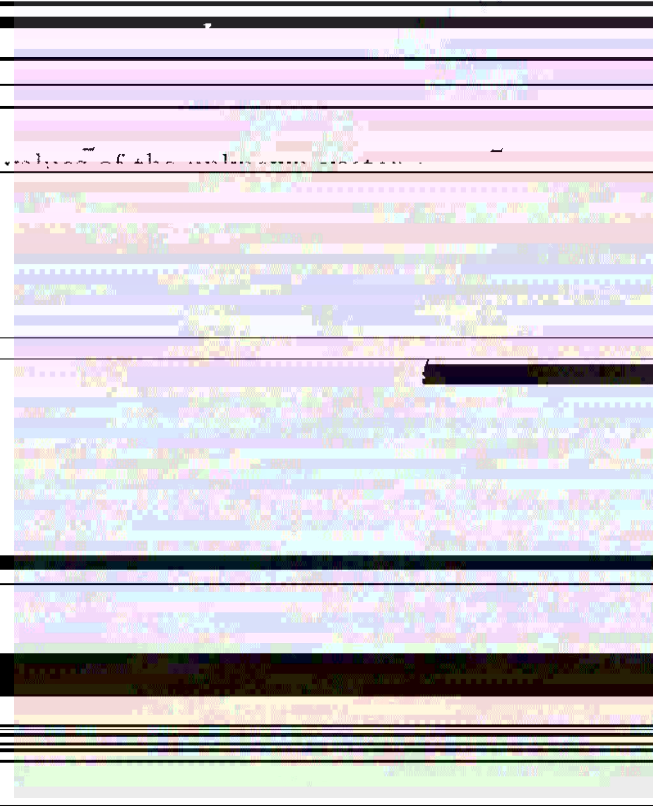
System of Euler

$n = 1$



where $\mu = \frac{1}{\mu_1 + \mu_2}$ and \tilde{a} is the

intermediate value of the unknown system.



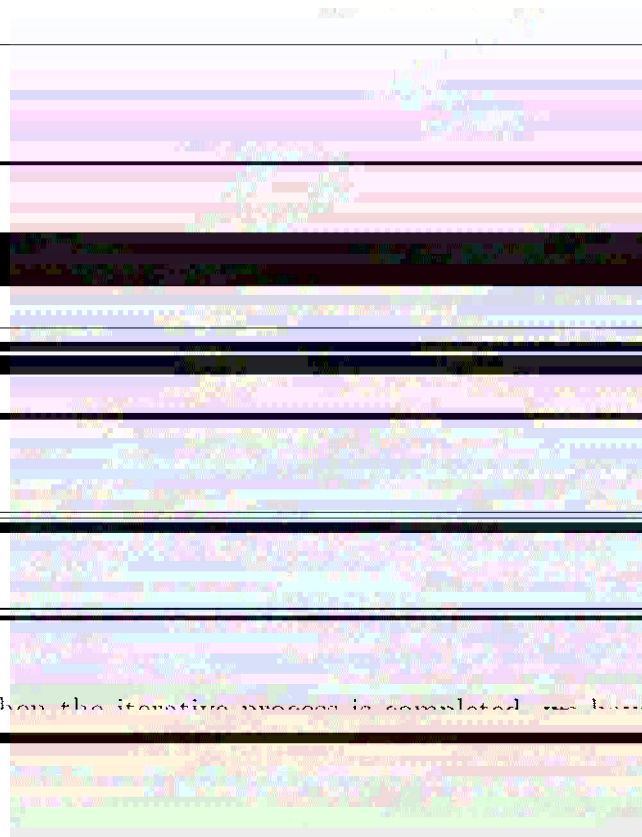
The sweep method for the solution of (2.3.6) is given by the following formulas

$$\tilde{q}_i = \alpha_i \tilde{q}_{i+1} + \beta_i,$$

$$i = 1, \dots, N_1 - 1.$$

$$\tilde{q}_{1,j} = \tilde{q}_{AD}(j).$$

In the QR scheme the solution of (2.3.6) is combined with (2.3.7)

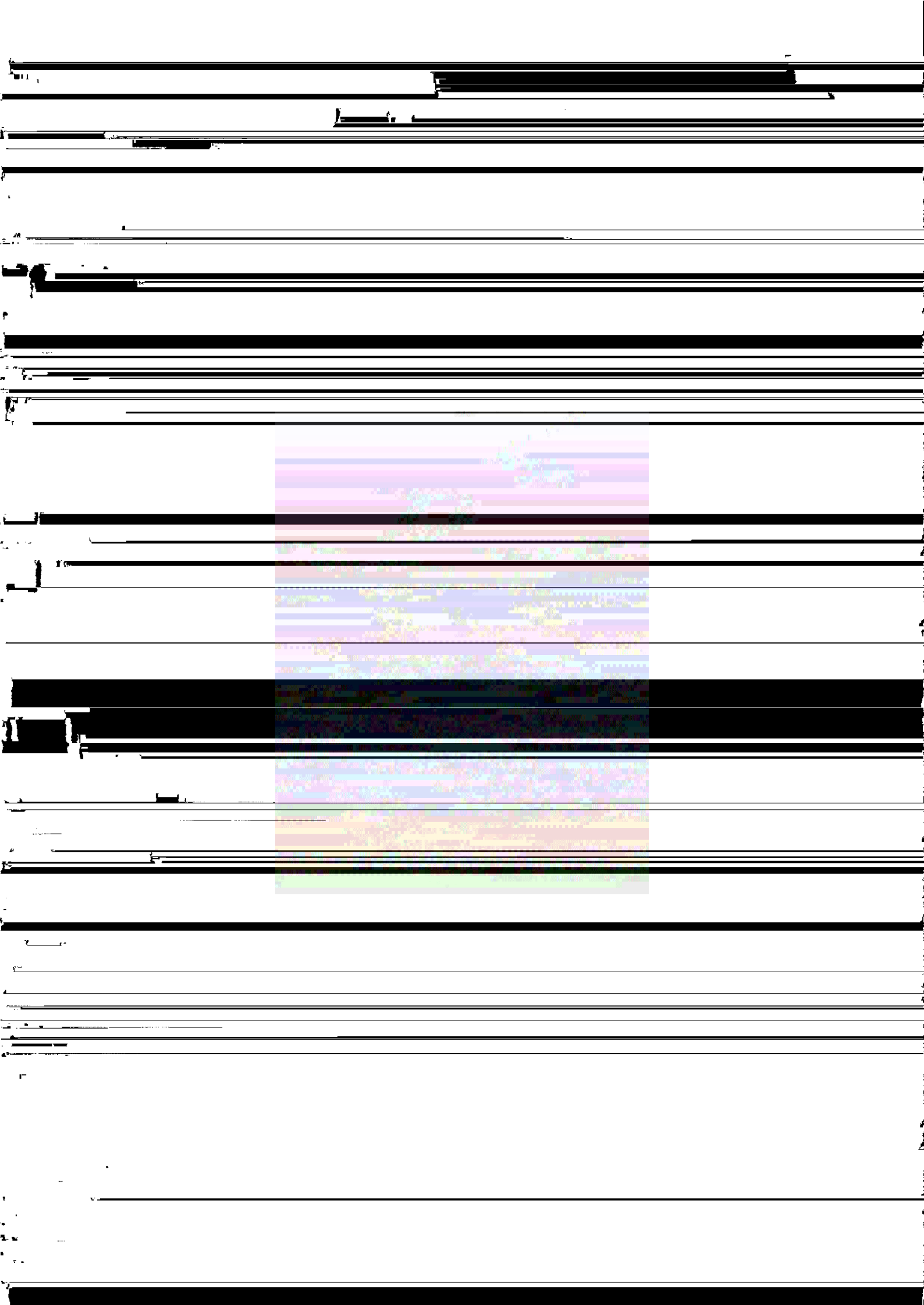


decidable. When the iterative process is completed, we have to transform back

tribution of the measure in the physical and computational domain. To find the



$$\left(\frac{\partial w}{\partial \varphi}\right)_{i,j-1} = \begin{cases} \frac{w_{i,j} - w_{i,j-2}}{2h_2} & : j \neq N_2, \\ \frac{-3w_{i,1} + 4w_{i,2} - w_{i,3}}{2h_2} & : i = 2. \end{cases}$$



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