

INPUT WEIGHTING FOR SISO SYSTEM WITH FEEDBACK PID CONTROLLER

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Abstract

This paper describes experimental studies of a regulating and tracking control strategy in which the attempt to improve the system performance is externally issued to the control loop. The control method can be viewed as the input compensating technique. The results illustrate strengths and weaknesses of the method. The method is quite attractive to industrial applications since it introduces minimum disruption to an existing control system.

Key words : PID control, input weighting, tracking, regulating.

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