

รายการอ้างอิง

- [1] R. Mur-Artal, J. M. M. Montiel, และ J. D. Tardós. (2015). ORB-SLAM: a Versatile and Accurate Monocular SLAM System. *IEEE Transactions on Robotics*.
- [2] R. Mur-Artal, และ J. D. Tardós. (2017). ORB-SLAM2: an Open-Source SLAM System for Monocular, Stereo and RGB-D Cameras. *IEEE Transactions on Robotics*.
- [3] B. Lee, N. Y. Ko, และ H. G. Yeom. (2022). Application of Visual Inertial Odometry for Pose Estimation of a Mobile Robot. *The 22nd International Conference on Control, Automation and Systems (ICCAS 2022)*. Busan, Korea: ICROS.
- [4] Elliott D. Kaplan, และ Christopher J. Hegarty. (2017). *Understanding GPS/GNSS: Principles and Applications (3rd ed.)*. Norwood, MA: Artech House.
- [5] F. O. Coelho, J. P. Carvalho, M. F. Pinto, และ A. L. Marcato. (2018). EKF and Computer Vision for Mobile Robot Localization. *13th APCA International Conference on Automatic Control and Soft Computing (CONTROLO 2018)*. Ponta Delgada, Azores, Portugal: IEEE.
- [6] G.-S. Cai, H.-Y. Lin, และ S.-F. Kao. (ม.ป.ป.). Mobile Robot Localization using GPS, IMU and Visual Odometry.
- [7] H. Kuang, X. Wang, X. Liu, X. Ma, และ R. Li. (2017). An Improved Robot's Localization and Mapping Method Based on ORB-SLAM. *10th International Symposium on Computational Intelligence and Design (ISCID)*. IEEE.
- [8] J. Delmerico, และ D. Scaramuzza. (2018). A Benchmark Comparison of Monocular Visual-Inertial Odometry Algorithms for Flying Robots. *IEEE International Conference on Robotics and Automation (ICRA 2018)*. IEEE.
- [9] Luxonis. (ม.ป.ป.). *Camera Calibration*. เข้าถึงได้จาก <https://docs.luxonis.com/hardware/platform/depth/calibration>
- [10] MakersPortal. (2019). *Calibration of an Inertial Measurement Unit (IMU) with Raspberry Pi – Part II*. เข้าถึงได้จาก <https://makersportal.com/blog/calibration-of-an-inertial-measurement-unit-imu-with-raspberry-pi-part-ii>

- [11] Roland Siegwart, และ Illah R. Nourbakhsh. (2004). *Introduction to Autonomous Mobile Robots*. Cambridge, MA: The MIT Press.
- [12] ROS.org. (ม.ป.ป.). *REP-105: Coordinate Frames for Mobile Platforms*. เข้าถึงได้จาก <https://www.ros.org/reps/rep-0105.html>
- [13] ROS.org. (ม.ป.ป.). *Robot Localization Package (ROS Melodic)*. เข้าถึงได้จาก https://docs.ros.org/en/melodic/api/robot_localization/html/index.html
- [14] Sebastian Thrun, Wolfram Burgard, และ Dieter Fox. (2005). *Probabilistic Robotics*. Cambridge, MA: The MIT Press.