

รายการอ้างอิง

- Hartley, R., & Zisserman, A. (2003). **Multiple view geometry in computer vision**. Cambridge university press.
- Li, H., Sima, C., Dai, J., Wang, W., Lu, L., Wang, H., ... & Qiao, Y. (2023). **Delving into the devils of bird's-eye-view perception: A review, evaluation and recipe**. IEEE Transactions on Pattern Analysis and Machine Intelligence.
- Shirley, P., Ashikhmin, M., & Marschner, S. (2009). **Fundamentals of computer graphics**. AK Peters/CRC Press.
- Redmon, J., Divvala, S., Girshick, R., & Farhadi, A. (2016). **You only look once: Unified, real-time object detection**. In Proceedings of the IEEE conference on computer vision and pattern recognition (pp. 779-788).
- Bochkovskiy, A., Wang, C. Y., & Liao, H. Y. M. (2020). **Yolov4: Optimal speed and accuracy of object detection**. arXiv preprint arXiv:2004.10934.
- Liu, W., Anguelov, D., Erhan, D., Szegedy, C., Reed, S., Fu, C. Y., & Berg, A. C. (2016). **Ssd: Single shot multibox detector**. In Computer Vision–ECCV 2016: 14th European Conference, Amsterdam, The Netherlands, October 11–14, 2016, Proceedings, Part I 14 (pp. 21-37). Springer International Publishing.
- He, K., Zhang, X., Ren, S., & Sun, J. (2016). **Deep residual learning for image recognition**. In Proceedings of the IEEE conference on computer vision and pattern recognition (pp. 770-778).
- Ren, S., He, K., Girshick, R., & Sun, J. (2015). **Faster r-cnn: Towards real-time object detection with region proposal networks**. Advances in neural information processing systems, 28.
- Girshick, R. B. (2015). **Fast R-CNN**. CoRR, abs/1504.08083. arXiv preprint arXiv:1504.08083.
- Redmon, J., & Farhadi, A. (2017). **YOLO9000: better, faster, stronger**. In Proceedings of the IEEE conference on computer vision and pattern recognition (pp. 7263-7271).

- Chen, R. C. (2019). **Automatic License Plate Recognition via sliding-window darknet-YOLO deep learning**. *Image and Vision Computing*, 87, 47-56.
- Redmon, J., & Farhadi, A. (2018). **Yolov3: An incremental improvement**. arXiv preprint arXiv:1804.02767.
- Bochkovskiy, A., Wang, C. Y., & Liao, H. Y. M. (2020). **Yolov4: Optimal speed and accuracy of object detection**. arXiv preprint arXiv:2004.10934.
- Ultralytics. (2020). **YOLOv5. [Online]**. Available: <https://github.com/ultralytics/yolov5>. [Accessed 03-Feb-2024].
- Li, C., Li, L., Jiang, H., Weng, K., Geng, Y., Li, L., ... & Wei, X. (2022). **YOLOv6: A single-stage object detection framework for industrial applications**. arXiv preprint arXiv:2209.02976.
- Wang, C. Y., Bochkovskiy, A., & Liao, H. Y. M. (2023). **YOLOv7: Trainable bag-of-freebies sets new state-of-the-art for real-time object detectors**. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition* (pp. 7464-7475).
- Wang, G., Chen, Y., An, P., Hong, H., Hu, J., & Huang, T. (2023). **UAV-YOLOv8: a small-object-detection model based on improved YOLOv8 for UAV aerial photography scenarios**. *Sensors*, 23(16), 7190.
- Xiao, F., Wang, H., Xu, Y., & Zhang, R. (2023). **Fruit Detection and Recognition Based on Deep Learning for Automatic Harvesting: An Overview and Review**. *Agronomy*, 13(6), 1625.
- Lou, H., Duan, X., Guo, J., Liu, H., Gu, J., Bi, L., & Chen, H. (2023). **DC-YOLOv8: Small-Size Object Detection Algorithm Based on Camera Sensor**. *Electronics*, 12(10), 2323.
- Ultralytics. (2023). **YOLOv8. [Online]**. Available: <https://github.com/ultralytics/yolov8>. [Accessed 03-Feb-2024].
- Pereira, R., Carvalho, G., Garrote, L., & Nunes, U. J. (2022). **Sort and deep-SORT based multi-object tracking for mobile robotics: Evaluation with new data association metrics**. *Applied Sciences*, 12(3), 1319.

- Ikomia. (2023). **Deep SORT Object Tracking Guide**. Ikomia Blog. Available at: <https://www.ikomia.ai/blog/deep-sort-object-tracking-guide>. [Accessed on 03-Feb-2024].
- Kuhn, H. W. (1955). **The Hungarian method for the assignment problem**. Naval research logistics quarterly, 2(1-2), 83-97.
- Ziegler, J., Bender, P., Dang, T., & Stiller, C. (2014, June). **Trajectory planning for Bertha—A local, continuous method**. In 2014 IEEE intelligent vehicles symposium proceedings (pp. 450-457). IEEE.
- Poggenhans, F., Pauls, J. H., Janosovits, J., Orf, S., Naumann, M., Kuhnt, F., & Mayr, M. (2018, November). **Lanelet2: A high-definition map framework for the future of automated driving**. In 2018 21st international conference on intelligent transportation systems (ITSC) (pp. 1672-1679). IEEE.
- Ebrahimi Soorchaei, B., Razzaghpour, M., Valiente, R., Raftari, A., & Fallah, Y. P. (2022). **High-Definition Map Representation Techniques for Automated Vehicles**. Electronics, 11(20), 3374.
- Naoki, A., Luis, Y., Eijiro, T., Yuki, Y., & Yoshiki, N. (2017). **Robust Localization Using 3D NDT Scan Matching with Experimentally Determined Uncertainty and Road Marker Matching**. In Proceedings of the IEEE Intelligent Vehicles Symposium (IV), Los Angeles, California, USA.
- Sijia, L., Jie, L., Jinmin, H., Haoru, L., & Yu, L. (2021). **Research on NDT-based Positioning for Autonomous Driving**. In Proceedings of the 5th International Workshop on Advances in Energy Science and Environment Engineering (AESEE 2021), Volume 257.
- Shirley, P., Ashikhmin, M., & Marschner, S. (2009). **Fundamentals of computer graphics**. AK Peters/CRC Press.
- Quigley, M., Conley, K., Gerkey, B., Faust, J., Foote, T., Leibs, J., Wheeler, R., & Ng, A. Y. (2009). **ROS: an open-source Robot Operating System**. ICRA workshop on open source software.
- Barber, E. L., Lundsberg, L. S., Belanger, K., Pettker, C. M., Funai, E. F., & Illuzzi, J. L. (2011). **Indications contributing to the increasing cesarean delivery rate**. Obstetrics & Gynecology, 118(1), 29-38.

- Toupet, O., Del Sesto, T., Ono, M., Myint, S., Vander Hook, J., & McHenry, M. (2020). **A ros-based simulator for testing the enhanced autonomous navigation of the mars 2020 rover**. 2020 IEEE Aerospace Conference.
- Hook, J., & McHenry, M. (2020, March). **A ros-based simulator for testing the enhanced autonomous navigation of the mars 2020 rover**. In *2020 IEEE Aerospace Conference* (pp. 1-11). IEEE